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Problem Represent each of the following combinations of units in the correct SI form using an appropriate prefix: (a) (b) (c) (d) Units Used: 10 10 N km 9 Gs 10 s 3 ks 10 s mN 10 ms 10 N s Solution: (a) m 3m 1 10 ms s m km ms s ...

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Solution: $\theta = \tan^{-1}(k)$ $\theta = 16.699^\circ$ $r_f = r \sin(\theta)$ $r_f = 0.5747$ in.
Equilibrium: $\sum F_y = 0$; $R_y - F = 0$ $R_y = F$ $R_y = 20.00$ lb $\sum F_x = 0$; $P \cos \theta - R_x = 0$
 $R_x = P$ $R^2 = x^2 + R_y^2 = P^2 + F^2$ Guess $P = 11$ lb Given $\theta = 30^\circ$ $P^2 + F^2 = r_f^2 + R^2$
 $r_f + R \cos \theta = P$ $P = \text{Find}(P)$ $P = 13.79$ lb. Problem 8- The collar fits loosely around a fixed shaft that has radius r .

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Solution: $I_x = 0$. a. 31 b. $x_a = 3$ c. $d = 1.07$ in
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Solution: $\theta = 180 \text{ deg}$ $\sum F_x = 0$ $F_1 \cos(\theta) + F_2 \cos(\theta) - F_3 = 0$

$F_1 = 61.4 \text{ lb}$ $\sum F_y = 0$ $F_1 \sin(\theta) + F_2 \sin(\theta) - F_4 = 0$

$\theta = 51.8 \text{ deg}$ $\theta = 6.8 \text{ deg}$. Problem 2- Resolve the force F_1 into

components acting along the u and v axes and determine the components.

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Solution: $M_A = F \sin(\theta) \cdot a$ $M_A = 11.7 \text{ kip ft}$ $M_B = F \sin(\theta) \cdot a$ $M_B = 11.7 \text{ kip ft}$

Also $b a = () \tan(\theta)$ $M_A = F \cos(\theta) \cdot b$ $M_A = 11.7 \text{ kip ft}$ $M_B = F \cos(\theta) \cdot b$ $M_B = 11.7$

kip ft?

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Solution: Initial Guesses. $F_{AB} = 1 \text{ lb}$ $F_{AD} = 1 \text{ lb}$ $F_{DC} = 1 \text{ lb}$. $F_{BC} = 1 \text{ lb}$ $F_{BD} = 1 \text{ lb}$ $F_{DE} = 1 \text{ lb}$. Given. Joint A: F_{AB} . F_{AD} . $\cos(\theta) = 0$; $P_1 = F_{AD}$

$\sin(\theta) = 0$. Joint B: F_{BC} . F_{AB} $= 0$ $P_2 = F_{BD}$ $= 0$. 441 © 2007

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11.3 Principle of Virtual Work for a System of Connected Rigid Bodies 571. 11.4 Conservative Forces 583. 11.5 Potential Energy 584. 11.6 Potential-Energy Criterion for Equilibrium 586. 11.7 Stability of Equilibrium Configuration 587 Appendix . A. Mathematical Review and Expressions . Fundamental Problems Partial Solutions and Answers

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